

## SF PRENTIC Series | Desktop Robot Model: SF7-K759

The ultra-compact SF PRENTIC series are compact and flexible tabletop robots that are powerful, fast, and efficient, enabling extremely precise and agile robots for various applications in the medium load class, no matter how small the parts are.

SF PRENTIC has a maximum load capacity of 7 kg and an arm span of 737.5 mm. With the introduction of the SF PRENTIC series, We are redefining the benchmark for robots in the tabletop class below 7 kg.

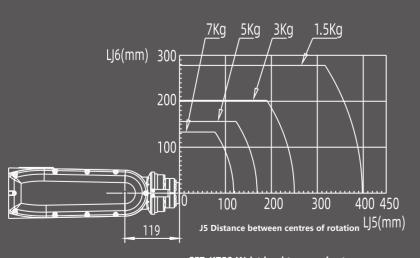
The SF PRENTIC series is ideal for applications in tight spaces such as 3C, handling, painting, welding, pick/pack, and assembly /distribution.

This desktop-class robot is tailored for the pursuit of performance and throughput.

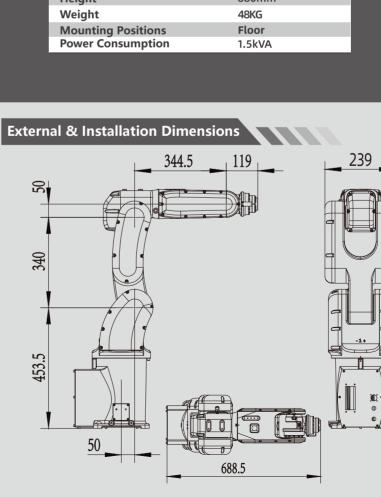


Model		SF7-K759
Structure		Vertically Articulated
Number of Axis		6
Radius		737.5mm
Payload		7kg
Repeatability		±0.04mm
Drive Mode		AC Servo Motor
Maximum Speed	J1 J2 J3 J4 J5 J6	305° /s 280° /s 300° /s 300° /s 406° /s 600° /s
Range of Motion	J1 J2 J3 J4 J5 J6	±171° +65° /-141° +170° /-66° ±180° ±119° ±360°
Allowable Moment	J4 J5 J6	15.6N.M 15.6N.M 8.5N.M
Allowable Inertia	J4 J5 J6	0.43kg.m2 0.43kg.m2 0.13kg.m2
Protection Rating		IP65
	Temp.	0-45°C
Operating	Humidity	Below 95%RH
Conditions	Vibration	Below 4.9m/s2
	Other	Eliminate Signal Noise
Base Size		210*235mm
Height		880mm
Weight		48KG
Mounting Positions		Floor
Power Consumption		1.5kVA

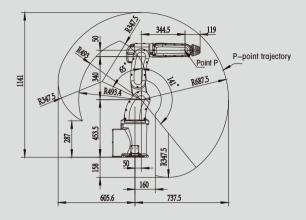
SF7-K759 Data Overview

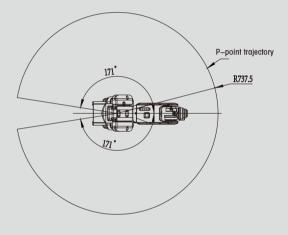


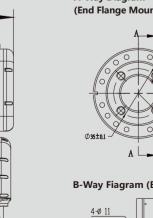
SF7-K759 Wrist load torque chart Note: The centre of gravity point of the load should be within the wrist torque diagram when in use



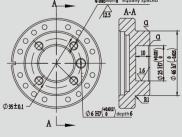
## SF7-K759 Range of Motion







A-Way Diagram (End Flange Mounting Dimensions)



B-Way Fiagram (Base Mounting Dimensions)

